

Digital Control Of Dynamic Systems

P.N. Paraskevopoulos

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provides students teachers and industrial engineers with the necessary steps in discretizing continuous systems It covers

fundamental concepts in sampling and reconstruction of signal and details the inspection method the direct division method the partial fraction expansion method the recurrence inversion method and the contour integration method The book also introduces the transfer function and the stability condition of discrete time systems in the closed loop Indeed it explains the global stability definition the algebraic stability criterion and the stability in the frequency domain The book also details the synthesis of digital controller for linear time invariant system and the use of a digital PID controller in practical speed control of a DC motor using an arduino card to encourage readers to explore new applied areas of digital control Dynamic Systems V56: Digital and Numeric Techniques and Their Application in Control Systems C.T. Leonides, 2012-12-02 Control and Dynamic Systems Advances in Theory and Applications Volume 56 Digital and Numeric Techniques and their Applications in Control Systems Part 2 of 2 covers the significant developments in digital and numerical techniques for the analysis and design of modern complex control systems This volume is composed of 12 chapters and starts with a description of the design techniques of linear constrained discrete time control systems. The subsequent chapters describe the techniques dealing with robust real time system identification the adaptive control algorithms and the utilization of methods from generalized interpolation and operator theory to deal with a wide range of problems in robust control These topics are followed by reviews f the decentralized control design for interconnected uncertain systems the computation of frequency response of descriptor systems by rational interpolation the techniques for the synthesis of multivariable feedback control laws and the effect of the initial condition in state estimation for discrete time linear systems Other chapters illustrate practical efficient and reliable numerical algorithms for robust multivariable control design of linear time invariant systems as well as a complete analysis of closed loop transfer recovery in discrete time systems using observer based controllers The last chapters provide the techniques in robust policy making in the global economic environment and the implications of robust control techniques for continuous time systems This book will prove useful to process control systems and design <u>Digital Control Systems</u> Ioan Doré Landau, Gianluca Zito, 2005-10-13 The extraordinary development of digital engineers computers microprocessors microcontrollers and their extensive use in control systems in all fields of applications has brought about important changes in the design of control systems Their performance and their low cost make them suitable for use in control systems of various kinds which demand far better capabilities and performances than those provided by analog controllers However in order really to take advantage of the capabilities of microprocessors it is not enough to reproduce the behavior of analog PID controllers One needs to implement specific and high performance model based control techniques developed for computer controlled systems techniques that have been extensively tested in practice In this context identification of a plant dynamic model from data is a fundamental step in the design of the control system The book takes into account the fact that the association of books with software and on line material is radically changing the teaching methods of the control discipline Despite its interactive character computer aided control design software requires the

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Modeling, Analysis, and Control of Dynamic Systems William J. Palm, III,1999-07-29 A Comprehensive Introduction to a Dynamic Field More modeling more controls more electrical and mechanical devices The second edition contains more coverage of key topics for a comprehensive introduction to dynamic systems and control This includes modeling and analysis techniques the fundamentals and applications of control systems transfer functions sensitivity and robust control and digital control Engineering design is also emphasized throughout the text with case studies design examples problems and extensive hardware coverage Key Features of the Second Edition Extensive coverage on modeling is expanded to four chapters The selection of engineering examples and the clear writing effectively relates the math methods to the real world Laplace transform response techniques are introduced as needed in the context of engineering applications. This approach clearly demonstrates the need for and the power of these techniques Case studies are integrated throughout the text to provide in depth treatment of practical engineering applications such as motion control system design electromechanical system design vehicle suspension design and aircraft response modes Optional sections at the end of each chapter introduce Matlab commands and applications relevant to the chapter's topics Digital controller design using Matlab is covered without the need for z transform theory Digital Control Systems Implementation and Computational Techniques, 1996-07-09 Praise for the Series This book will be a useful reference to control engineers and researchers The papers contained cover well the recent advances in the field of modern control theory IEEE Group Correspondence This book will help all those researchers who valiantly try to keep abreast of what is new in the theory and practice of optimal control Control Applied Digital Control J. R. Leigh, 2006-06-23 An essential core text this volume develops theoretical foundations and explains how control

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