

# INDUSTRIAL VALVE AND ENGINEERING SUPPLIES (Pty) Ltd.(IVES)

## VALVE AND ENGINEERING MERCHANT COMPANY (Pty) Ltd (VEMCO)



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## BMC BALANCING VALVES FLANGED

### 9201 FIXED ORIFICE DOUBLE REGULATING VALVE (FODRV)

- Pressure Rating: PN16
- Working Medium: Water
- Working Temperature: -10~120°C
- Flange to BSEN1092-2
- Comply with BS7350

#### Specification

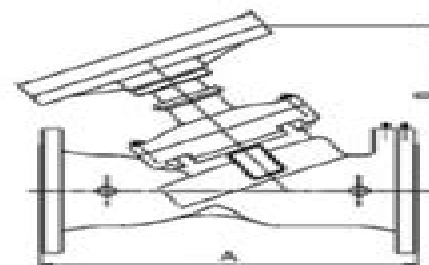
Y-Pattern globe valve with a characterised throttling disc and ends flanged to BSEN 1092-2 PN16.

The valve opening may be set to control flow at a pre-determined rate. Operation of the valve is by means of a handwheel incorporating a micrometer device.

The Double Regulating feature allows the valve to be used for isolation and to be reopened to its pre-set position to maintain required flow rate.

#### Application

In two unit systems, the 9201 has sufficient authority to regulate flow in circuits incorporating a flow measurement device.



#### Bill of Materials

Description	Material	Spec	QTY
Body	Ductile Iron	EN-CL 1000	1.0
Disc	Ductile Iron	EN-CL 1000	1.0
Stem	Stainless Steel	A304/316	1.0
Disc	EPDM Coated Di	EN-CL 1000	1.0
Stem	Brass	EN-CL 1000	1.0
Stem	Ductile Iron	EN-CL 1000	1.0
Stem Nut	Brass	EN-CL 1000	1.0
Handwheel	Ductile Iron	EN-CL 1000	1.0
Seal O-Ring	Brass	EN-CL 1000	1.0
Seal O-Ring	Brass	EN-CL 1000	1.0
Seal O-Ring	Brass	EN-CL 1000	1.0
Seal O-Ring	Brass	EN-CL 1000	1.0

#### Dimensions & Coefficients

9201							
DN	INCH	A	B	F low (m)	F low	F high (m)	F high
40	1 1/2"	200	200	10.4	10.4	10.4	10.4
50	2"	250	250	11.2	11.2	11.2	11.2
65	2 1/2"	300	300	12.2	12.2	12.2	12.2
80	3"	350	350	13.2	13.2	13.2	13.2
100	4"	450	450	15.2	15.2	15.2	15.2
125	5"	550	550	17.2	17.2	17.2	17.2
150	6"	650	650	19.2	19.2	19.2	19.2
200	8"	850	850	23.2	23.2	23.2	23.2
250	10"	1050	1050	27.2	27.2	27.2	27.2
300	12"	1250	1250	31.2	31.2	31.2	31.2

All Specifications are subject to change without notice

Break Away  
VALVES

# TECHNOLOGY AT ITS BEST

# Balancing In Mechanotechnics

**John Bernard Wilcox**



## Balancing In Mechanotechnics:

**Dynamic Balancing of Mechanisms and Synthesizing of Parallel Robots** Dan Zhang,Bin Wei,2015-10-20 This book covers the state of the art technologies in dynamic balancing of mechanisms with minimum increase of mass and inertia The synthesis of parallel robots based on the Decomposition and Integration concept is also covered in detail The latest advances are described including different balancing principles design of reactionless mechanisms with minimum increase of mass and inertia and synthesizing parallel robots This is an ideal book for mechanical engineering students and researchers who are interested in the dynamic balancing of mechanisms and synthesizing of parallel robots This book also Broadens reader understanding of the synthesis of parallel robots based on the Decomposition and Integration concept Reinforces basic principles with detailed coverage of different balancing principles including input torque balancing mechanisms Reviews exhaustively the key recent research into the design of reactionless mechanisms with minimum increase of mass and inertia such as the design of reactionless mechanisms with auxiliary parallelograms the design of reactionless mechanisms with flywheels and the design of reactionless mechanisms by symmetrical structure design     The Sociological Review ,1929

*South African national bibliography* ,1999 Classified list with author and title index     *Engineering Balance* Jonathan E. Abbott,Massachusetts Institute of Technology. Department of Mechanical Engineering,2014 This work presents a view of balance useful for mechanical engineers Mechanical engineers often need to make quick intelligent decisions using conceptual and physical understanding The typical mechanical engineering instruction usually provides a good basis for back of the envelope calculations especially for mechanical systems however one exception to this case is in the field of dynamics and control Dynamics and control is generally taught with much math modelling most systems with differential equations Although math is useful for designing control systems when designing products for people who act as sophisticated controllers the engineer needs a more general understanding of balance This work presents a conceptual intuitive way to break the act of balance into distinct mechanisms and thereby quickly evaluate how a system balances     *Mechanical Balancing of Rotating Bodies* British Standards Institution,1984     **Three Component Balancing Apparatus for Use in Hydraulic Laboratories** Adnan A. Halet,1932     **International Books in Print** ,1991     **A Study of the Carwen Olsen Type Balancing Machine** Charles Mathew Perkins,1929     **Dynamic Balancing of Rotating Machinery** John Bernard Wilcox,1967     *An Automatic Dynamic-balancing Device Using Controlled Electric Discharges for Metal Removal* David Bates Russell,1964     **Gisholt Method of Balancing** Gisholt Machine Company,1926     *A Treatise on the Art of Balancing the Rotating Parts of Machinery ...* Defiance Machine Works,1881     Overhaul and Demonstration of the Gisholt Dynetric Balancing Machine Theron E. Bastian,1957     *Delay and Uncertainty in Human Balancing Tasks* Tamás Insperger,John Milton,2021-10-18 This book demonstrates how delay differential equations DDEs can be used to compliment the laboratory investigation of human balancing tasks This approach is made accessible to non specialists by comparing

mathematical predictions and experimental observations For example the observation that a longer pole is easier to balance on a fingertip than a shorter one demonstrates the essential role played by a time delay in the balance control mechanism Another balancing task considered is postural sway during quiet standing With the inverted pendulum as the driver and the feedback control depending on state variables or on an internal model the feedback can be identified by determining a critical pendulum length and or a critical delay This approach is used to identify the nature of the feedback for the pole balancing and postural sway examples Motivated by the question of how the nervous system deals with these feedback control challenges there is a discussion of microchaotic fluctuations in balance control and how robust control can be achieved in the face of uncertainties in the estimation of control parameters The final chapter suggests some topics for future research Each chapter includes an abstract and a point by point summary of the main concepts that have been established A particularly useful numerical integration method for the DDEs that arise in balance control is semi discretization This method is described and a MATLAB template is provided This book will be a useful source for anyone studying balance in humans other bipedal organisms and humanoid robots Much of the material has been used by the authors to teach senior undergraduates in computational neuroscience and students in bio systems biomedical mechanical and neural engineering

Questions on the Development of Universal Balancing Equipment L. N. Ozerov, FOREIGN TECHNOLOGY DIV WRIGHT-PATTERSON AFB OHIO., 1967 Balancing machines MDB 1A MDU 2 MDU 3 and MDU 210 for aeronautical rotors and balancing machines MDBG 1 and UUG 3 for gyroscope rotors are described MDB 1A two movable supports for balancing rotors of 15 100 kg Electronic frequency pickup to 10 15cps consists of a line filter in a special circuit MDU 2 built in 1952 was the first machine using stationary supports to pick up unbalanced forces with piezoelectric pickups Rotors 5 100 kg A light beam reflected from the rotor onto a photocell and an electronic measuring system serve as the unbalance pickup MDU 3 same MDU 2 for rotors of 5 500 kg but difficulties encountered with rotors above 100 kg led to development of MDU 210 which has stationary support rotors 10 1000 kg Electronic measuring devices permit balancing of above rotors within 1 10 gm cm Maximum rotor diameter 1400 mm speed 800 and 450 RPM MDBG 1 for gyroscope rotor balancing Has mechanical frequency isolation with optical pickup and secondary vibration system for better sensitivity No indication of exact place of unbalance UUG 3 built in 1952 for gyroscope rotor balancing Has mechano optical system ofr picking up amount and place of unbalance Uses mirrors on secondary vibration systems that rotate mirrors which project light beam reflected from rotor on a screen Diameter of light circle indicates size location of blank rotor marking indicates place of unbalance Author

*High-Speed Balancing Technology and Equipment* Sheping Tian, Yewu Wang, 2020-01-03 This book gives an introduction to the high speed balancing technology and equipment of flexible rotors explaining the fundamental concepts and principles construction and basic design of high speed balancing machines and overspeed test camber as well as the technical specifications of DG series high speed balancing machines This book is intended for engineering staffs and researchers in the

field of high speed balancing as well as senior undergraduates graduate students and university teachers      **Practical Balancing of Rotating Machinery** Derek Norfield,2011-04-18 Rotating machinery eg pumps motors compressors is normally manufactured to precise measurements but there comes a point when the costs of manufacture mean that further precision is not cost effective and thus any slight imbalance inherent in the machine will need to be attended to after manufacture When such machinery is in operation often at very high speeds of thousands of revs per minute any imbalance will set up vibration and often noise In addition such imbalance will cause extra wear and loss of efficiency in the machine The answer is to balance the affected parts of the machine so that it operates smoothly and efficiently This book is a practical account of such balancing techniques e g how to balance a rotor how to set up and verify performance of a balancing machine and procedures for on site balancing In addition other common causes of vibration will be covered e g misalignment bad bearings and looseness This book is the distillation of a successful course run by the author and developed over 20 years University engineering departments do not teach balancing techniques beyond the very basic and there is a need for educators and engineers to have a practical book available on the topic A practical book which will help the reader understand the importance of balance in today s high technology world Outlines the history of dynamic balancing and other vibration reduction techniques Profusely illustrated throughout      **Design Criteria for Balancing Machine Tooling** EG-1A Balancing Committee,2012 This document recommends general designs tolerances limits of application and suitable tooling fixtures and accessories for mounting and driving jet engine rotors on horizontal and vertical balancing machines This document has been determined to contain basic and stable technology which is not dynamic in nature This document was superseded by ARP4163      **Computational Kinematics** Andrés Kecskeméthy,Andreas Müller,2009-05-20 Computational kinematics is an enthralling area of science with a rich spectrum of problems at the junction of mechanics robotics computer science mathematics and computer graphics The present book collects up to date methods as presented during the Fifth International Workshop on Computational Kinematics CK2009 held at the University of Duisburg Essen Germany The covered topics include design and optimization of cable driven robots analysis of parallel manipulators motion planning numerical methods for mechanism calibration and optimization geometric approaches to mechanism analysis and design synthesis of mechanisms kinematical issues in biomechanics balancing and construction of novel mechanical devices detection and treatment of singularities as well as computational methods for gear design The results should be of interest for practicing and research engineers as well as Ph D students from the fields of mechanical and electrical engineering computer science and computer graphics      **Control Mechanics and Balance** Cicely Farrer,2014

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## **Balancing In Mechanotechnics Introduction**

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