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**\*6-1.** Determine the force in each member of the truss, and state if the members are in tension or compression.



**Method of Joints:** We will begin by analyzing the equilibrium of joint *D*, and then proceed to analyze joints *C* and *E*.

**Joint *D*:** From geometry,  $\theta = \tan^{-1}\left(\frac{1}{2}\right) = 26.57^\circ$ . Thus, from the free-body diagram in Fig. *a*,

$$\begin{aligned} \sum F_x = 0; \quad 600 - F_{DC} \sin 26.57^\circ &= 0 & \text{Ans.} \\ F_{DC} &= 1341.64 \text{ N} = 1.34 \text{ kN (C)} \\ + \uparrow \sum F_y = 0; \quad 1341.64 \cos 26.57^\circ - F_{DE} &= 0 & \text{Ans.} \\ F_{DE} &= 1200 \text{ N} = 1.20 \text{ kN (T)} \end{aligned}$$

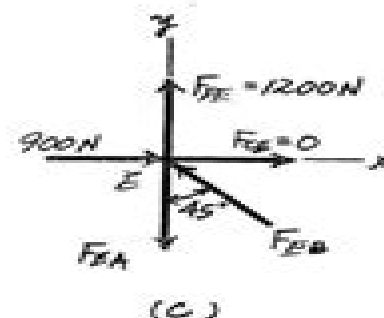
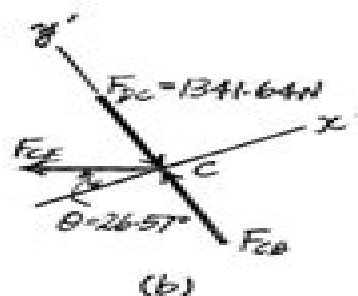
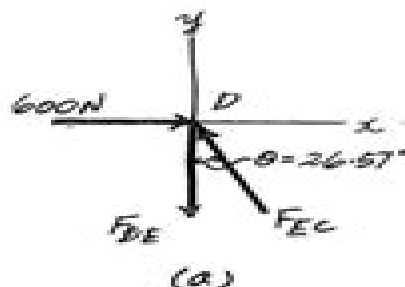
**Joint *C*:** From the free-body diagram in Fig. *b*,

$$\begin{aligned} + \nearrow \sum F_{x'} = 0; \quad -F_{CE} \cos 26.57^\circ &= 0 & \text{Ans.} \\ F_{CE} &= 0 \\ + \nearrow \sum F_{y'} = 0; \quad F_{CB} - 1341.64 &= 0 & \text{Ans.} \\ F_{CB} &= 1341.64 \text{ N} = 1.34 \text{ kN (C)} \end{aligned}$$

**Joint *E*:** From the free-body diagram in Fig. *c*,

$$\begin{aligned} \sum F_x = 0; \quad 900 - F_{EB} \sin 45^\circ &= 0 & \text{Ans.} \\ F_{EB} &= 1272.79 \text{ N} = 1.27 \text{ kN (C)} \\ + \uparrow \sum F_y = 0; \quad 1200 + 1272.79 \cos 45^\circ - F_{EA} &= 0 & \text{Ans.} \\ F_{EA} &= 2090 \text{ N} = 2.09 \text{ kN (T)} \end{aligned}$$

**Note:** The equilibrium analysis of joint *A* can be used to determine the components of support reaction at *A*.



# Chapter Statics Solutions

**Lewis Jerome Johnson**



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**Illustrated Seismic Processing, Volume 2: Preimaging** Stephen Hill, Andreas Rüger, 2020-12-01 Provides a foundation for understanding the fascinating field of seismic processing addressing that portion which precedes migration Written for the non expert this volume reveals the limitations and potential pitfalls of seismic data explains seismic processing operations as a series of solutions to problems and more An elementary text-book of mechanics. [With] Solutions of problems Richard Wormell (Science teacher), 1892 *Statics and Rotational Dynamics of Composite Beams* Mehrdaad Ghorashi, 2016-02-06 This book presents a comprehensive study of the nonlinear statics and dynamics of composite beams and consists of solutions with and without active elements embedded in the beams The static solution provides the initial conditions for the dynamic analysis The dynamic problems considered include the analyses of clamped hingeless and articulated hinged accelerating rotating beams Two independent numerical solutions for the steady state and the transient responses are presented The author illustrates that the transient solution of the nonlinear formulation of accelerating rotating beam converges to the steady state solution obtained by the shooting method Other key areas considered include calculation of the effect of perturbing the steady state solution coupled nonlinear flap lag dynamics of a rotating articulated beam with hinge offset and aerodynamic damping and static and dynamic responses of nonlinear composite beams with embedded anisotropic piezo composite actuators The book is intended as a thorough study of nonlinear elasticity of slender beams and is targeted to researchers graduate students and practicing engineers in the fields of structural dynamics aerospace structures and mechanical engineering Principles of Microelectromechanical Systems Ki Bang Lee, 2011-03-21 The building blocks of MEMS design through closed form solutions Microelectromechanical Systems or MEMS is the technology of very small systems it is found in everything from inkjet printers and cars to cell phones digital cameras and medical equipment This book describes the principles of MEMS via a unified approach and closed form solutions to micromechanical problems which have been recently developed by the author and go beyond what is available in other texts The closed form solutions allow the reader to easily understand the linear and nonlinear behaviors of MEMS and their design applications Beginning with an overview of MEMS the opening chapter also presents dimensional analysis that provides basic dimensionless parameters existing in large and small scale worlds The book then explains microfabrication which presents knowledge on the common fabrication process to design realistic MEMS From there coverage includes Statics force and moment acting on mechanical structures in static equilibrium Static behaviors of structures consisting of mechanical elements Dynamic responses of the mechanical structures by the solving of linear as well as nonlinear governing equations Fluid flow in MEMS and the evaluation of damping force acting on the moving structures Basic equations of electromagnetics that govern the electrical behavior of MEMS Combining the MEMS building blocks to form actuators and sensors for a specific purpose All chapters from first to last use a unified approach in which equations in previous chapters

are used in the derivations of closed form solutions in later chapters This helps readers to easily understand the problems to be solved and the derived solutions In addition theoretical models for the elements and systems in the later chapters are provided and solutions for the static and dynamic responses are obtained in closed forms This book is designed for senior or graduate students in electrical and mechanical engineering researchers in MEMS and engineers from industry It is ideal for radio frequency electronics sensor specialists who for design purposes would like to forego numerical nonlinear mechanical simulations The closed form solution approach will also appeal to device designers interested in performing large scale parametric analysis

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