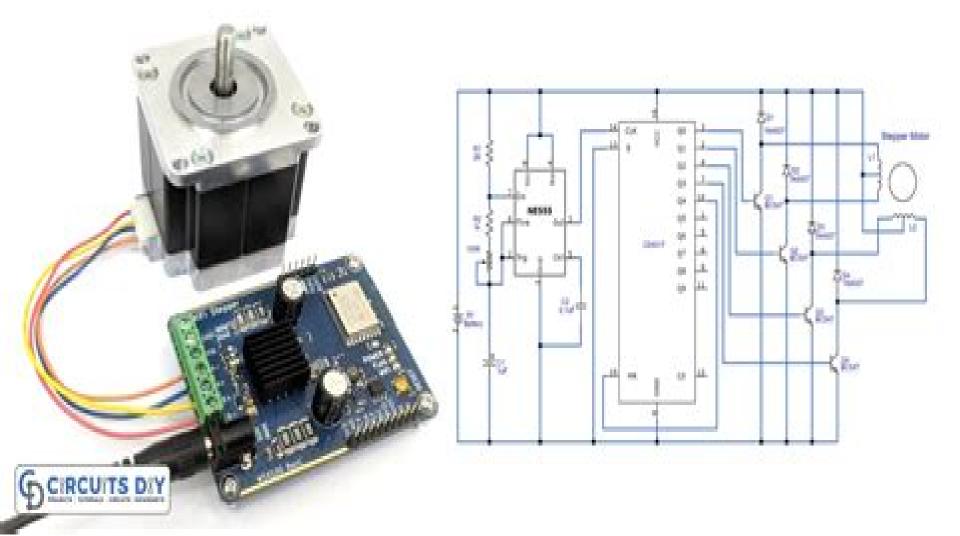
# Stepper Motor Controller



# **Chapter 1 Stepper Motor Control**

**R Barnett** 

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Electromechanical Motion Systems Frederick G. Moritz, 2014-01-28 An introductory reference covering the devices simulations and limitations in the control of servo systems Linking theoretical material with real world applications this book provides a valuable introduction to motion system design The book begins with an overview of classic theory its advantages and limitations before showing how classic limitations can be overcome with complete system simulation. The ability to efficiently vary system parameters such as inertia friction dead band damping and quickly determine their effect on performance stability efficiency is also described The author presents a detailed review of major component characteristics and limitations as they relate to system design and simulation The use of computer simulation throughout the book will familiarize the reader as to how this contributes to efficient system design how it avoids potential design flaws and saves both time and expense throughout the design process The comprehensive coverage of topics makes the book ideal for professionals who need to apply theory to real world situations as well as students who wish to enhance their understanding of the topic Covers both theory and practical information at an introductory level allowing readers to advance to further topics having obtained a strong grounding in the subject Provides a connection between classic servo technology and the evolution of computer control and simulation VisSim demonstration material available on an accompanying website enabling Industrial Automation David W. Pessen, 1991-01-16 The first book to readers to experiment with system examples combine all of the various topics relevant to low cost automation Practical approach covers methods immediately applicable to industrial problems showing how to select the most appropriate control method for a given application then design the necessary circuit Focuses on the control circuits and devices electronic electro mechanical or pneumatic used in small to mid size systems Stress is on on off binary control as opposed to continuous feedback analog control Discusses well known procedures and their modifications and a number of original techniques and circuit design methods Covers flexible automation including the use of microcomputers Mechanisms and Mechanical Devices Sourcebook, Fourth Edition Neil Sclater, Nicholas Chironis, 2007-01-01 Over 2000 drawings make this sourcebook a gold mine of information for learning and innovating in mechanical design The fourth edition of this unique engineering reference book covers the past present and future of mechanisms and mechanical devices Among the thousands of proven mechanisms illustrated and described are many suitable for recycling into new mechanical electromechanical or mechatronic products and systems Overviews of robotics rapid prototyping MEMS and nanotechnology will get you up to speed on these cutting edge technologies Easy to read tutorial chapters on the basics of mechanisms and motion control will introduce those subjects to you or refresh your knowledge of them Comprehensive index to speed your search for topics of interest Glossaries of terms for gears cams mechanisms and robotics New industrial robot specifications and applications Mobile robots for exploration scientific research and defense INSIDE Mechanisms and Mechanical Devices Sourcebook 4th Edition Basics of Mechanisms Motion Control Systems Industrial Robots Mobile Robots Drives and Mechanisms That Include Linkages Gears Cams Genevas and Ratchets Clutches and Brakes Devices That Latch Fasten and Clamp Chains Belts Springs and Screws Shaft Couplings and Connections Machines That Perform Specific Motions or Package Convey Handle or Assure Safety Systems for Torque Speed Tension and Limit Control Pneumatic Hydraulic Electric and Electronic Instruments and Controls Computer Aided Design Power Transmission Design ,1994 Concepts Rapid Prototyping New Directions in Mechanical Engineering

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