Automation Control Development with Capstone Projects

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I. Abstract

This article presents the development of the automation control projects developed in the Mechanical Engineering Technology Program of the Engineering Technology Department at Old Dominion University. These capstone projects are designed to help students gain industrial application experiences on design, test, and implementation. Two projects on automation controls are the focus of this article: (1) an automatic ship-bottom blasting machine and (2) a fully automated Car Jack. Three major topics are presented in each project: (1) introduction of the background, (2) methods to solve the problems in mechanical designs and automation controls such as hydraulic circuit and/or PLC programming, and (3) implementation and test results.

II. Introduction

The course objectives of Automation and Controls that offered in the Mechanical Engineering Technology Program of the Department of Engineering Technology at Old Dominion University are:

- Pneumatic components and pneumatic circuit designs.
- (2) Feedbacks from electrical sensors and related ladder diagrams.
- (3) Introduction to Programmable Logical Controllers (PLC) and PLC [1][2] programming.
- (4) Integration of pneumatic, electrical, and/or hydraulic components with PLC programming controls.

To ensure students have hands-on experiences in this course, a two-hour/week lab is also required to teach the students with integrate mechanical, pneumatic, and electrical components in ladder diagrams and PLC programming. Basically, the lab includes three main sessions: (1) four weeks of pneumatic applications, (2) four weeks of pneumatic components, electrical sensors, and ladder diagrams, and (3) five weeks of PLC programming using IDEC [3] and TRiLOGI [4] PLCs. In addition, the simulation software of Automation Studio [5] is also used in each project so that students can check their designs before the actual implementation. Depending on the

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Robotic Sailing Alexander Schlaefer, Ole Blaurock, 2011-07-15 While sailing has a long tradition both as a means of transportation and as a sport robotic sailing is a fairly new area of research One of its unique characteristics is the use of wind for propulsion On the one hand this allows for long range and long term autonomy On the other hand the dependency on changing winds presents a serious challenge for short and long term planning collision avoidance and boat control Moreover building a robust and seaworthy sailing robot is no simple task leading to a truly interdisciplinary engineering problem These proceedings summarize the state of the art as presented at the International Robotic Sailing Conference 2011 Following an overview of the history of autonomous sailing a number of recent boat designs is presented ranging from small one design boats to vessels built to cross the Atlantic Ocean Subsequently various aspects of system design and validation are discussed further highlighting the interdisciplinary nature of the field Finally methods for collision avoidance localization and route planning are covered Master One Skill, Monetize It Fully. A Deep-Focus Growth System That Works Ahmed Musa, 2025-05-30 You don't need 100 skills You need one skill mastered so deeply people can tignore you Master One Skill Monetize It Fully is your laser focused guide to going all in on your one thing and squeezing every drop of income impact and opportunity out of it Forget the shiny objects Ditch the learn everything trap This book is about deep focus high leverage and massive payoffs Inside you ll discover How to identify the one skill that unlocks doors and pays you for life The exact system to master it faster than 99% of people How to stack income streams around your skill without losing focus Why becoming the best beats being a jack of all trades every time This isn t hustle porn This is clarity power and cash on demand Read it if you re tired of dabbling second guessing or chasing trends Read it if you re ready to own your lane and dominate Because when you master one skill and build your life around it everything changes SME Technical Paper Society of Manufacturing Engineers, 2005 Congressional Record United States. Congress, 1999 CAD/CAM, Robotics, and Factories of the Future '90: Flexible automation Suren N. Dwivedi, Alok K. Verma, John E. Sneckenberger, 1991 Contents Volume 2 I Factory Enhancements From the Existing Manufacturing System to CIM Flexible Manufacturing System in Manufacture of Precision Engineering Components Key Issues in Implementation A Survey of CIM Strategic Planning in U S Industry Modelling and Optimization of a Flexible Manufacturing System Computer Based Safety System for the FMS Management Logic CIM Repositories The Selection and Prospect of CAD CAM System for Diesel Engine Design and Manufacturing A Model for the Factory of the Future for Industrialized Housing Enabling Automation Technologies for an Automated Mail Facility of the Future Some Optimization Problems of Scheduling in a Flexible Manufacturing System Some Methods of Modeling for Computer Integrated Workshop Combined Procedures for Simulation of Manufacturing Systems Expert Systems in CIM II Production Planning A Taxonomy on Event Driven Production Systems An Improved Lot Sizing Policy for Variable Demand Simulation for Real Time Control Advantages Potential Pitfalls Opportunities Decomposition

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instrumentation in the light of growing interest in and need for teleworking remote services and collaborative working environments as a result of the globalization of education The book also discusses guidelines for education in university level courses for these topics Federal Register ,2000-06-08 Computerworld ,1981-09-21 For more than 40 years Computerworld has been the leading source of technology news and information for IT influencers worldwide Computerworld s award winning Web site Computerworld com twice monthly publication focused conference series and custom research form the hub of the world's largest global IT media network *Proceedings* American Society for Engineering Education. Annual Air Traffic Control Association Fall Conference Proceedings Air Traffic Control Conference, 1993 Winter Annual Meeting American Society of Mechanical Engineers, 1998 Association. Fall Conference, 2001 Paper **Proceedings. College Industry Education Conference** ,1990 PM Network ,1998 The Vertical Farm Kheir Al-Kodmany, Andrew Keong Ng, Abel Tablada, Chittaranjan Kole, 2024-10-25 Amid economic uncertainties fluctuating oil prices and a rising environmental consciousness the need for sustainable and efficient food production has become dire The Vertical Farm Scientific Advances and Technological Developments systematically navigates the realm of vertical farming VF rooted in a robust scientific foundation Unveiling the intricate convergence of plant biology environmental science and agronomy it provides a profound understanding of contemporary agriculture. The book spans lighting systems and climate control mechanisms focusing on sustainability From small urban initiatives to significant commercial endeavors real world case studies showcase VF s adaptability scalability and resilience Addressing multiple challenges the book explores economic considerations and public perceptions recognizing their roles in fostering meaningful advancements in agricultural innovation A volume in the Nextgen Agriculture series this book is valuable to scientists practitioners and students in urban agriculture and planning horticulture engineering landscape architecture and plant technology sciences Annual **Index/abstracts of SAE Technical Papers** ,2006 **FIE '98, Tempe, Arizona** ,1998 **IECON '01** IEEE Industrial Electronics Society. Conference, 2001 ASEE Annual Conference Proceedings American Society for Engineering Education. Conference, 2005 Annual Conference & Exposition American Society for Engineering Education, 2005

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